

LituanicaSAT-1: lessons learned from the first Lithuanian satellite mission

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Background story







Background story



Our secret ingredients for a successful mission:

- Work hard
- Do teambuilding
- Have passion in what you are doing





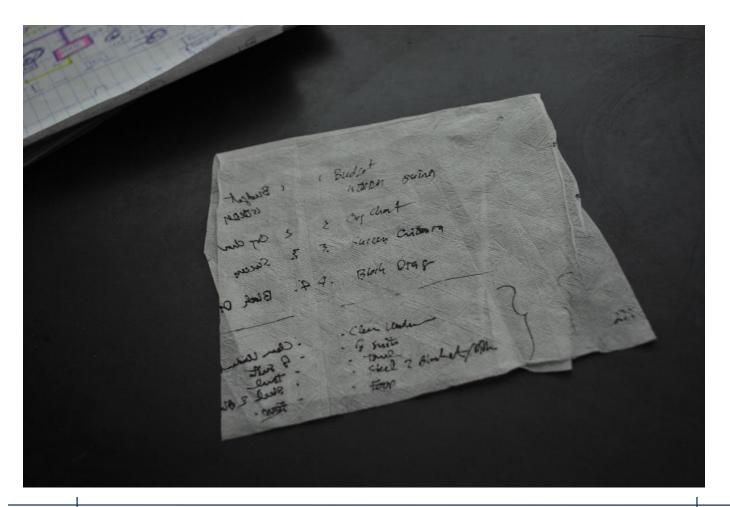




Background story



....and don't forget to use coffee brakes visely





Mission Statement (or plan on nampkin)



- To build and launch first Lithuanian satellite of 1U standard CubeSat size
- > To develop infrastructure and gain know how joining industry and academia
- To honour the **80**th **Anniversary** (July 15, 2013) of the flight across the Atlantic by Lithuanian pilots Steponas Darius and Stasys Girėnas.



Project Managment





















Mission Objectives



Primary Mission Objective

 To build and launch a first Lithuanian 1U size cubesat and send Lithuania's first message from space

Secondary Mission Objectives

- To provide university students and young engineers knowledge & real hands-on experience in satellite engineering
- To develop and test in space cubesat on board control and data handling sub-system
- To take pictures using on-board camera and downlink to the ground station
- To test an amateur radio FM voice repeater.



Mission Success Criteria



Minimum Success Criteria

- NASA PSRP approval and delivery of the cubesat to the ISS
- Launch cubesat from ISS by the JEM Remote Manipulator System (JEMRMS)
- System initialization and antenna deployment after time-out
- Transmit telemetry data (RF Morse code beacon or packet radio)

Nominal Success Criteria

- Establish two-way communication with ground station
- Turn on the FM voice repeater

Comprehensive Success Criteria

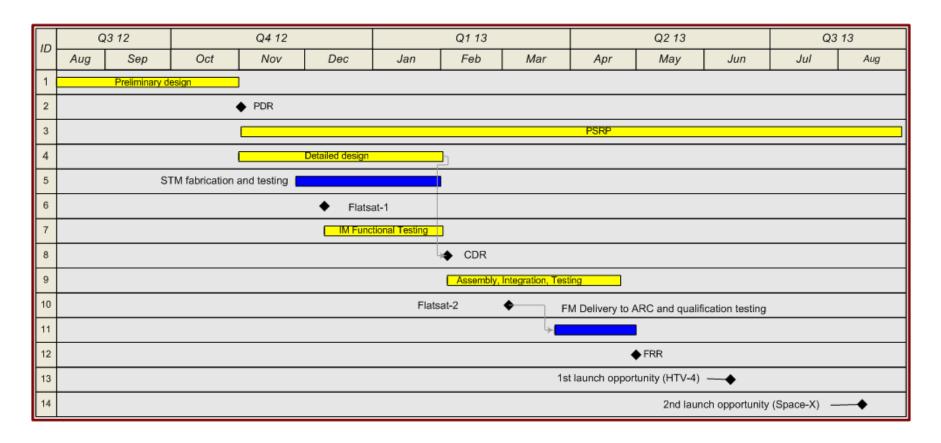
Take pictures with camera and downlink data to the ground station



Schedule – Baseline 1



Very optimistic!

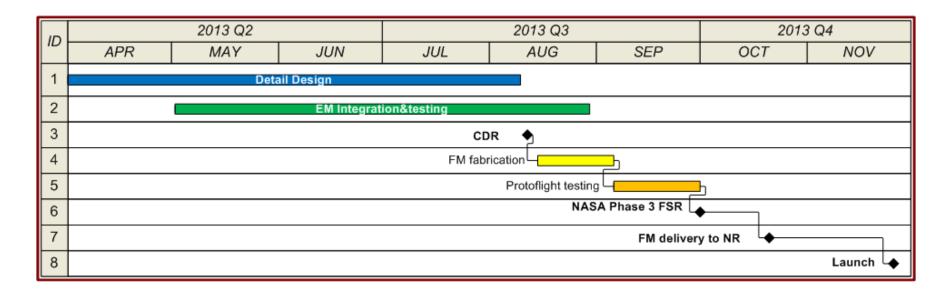




Schedule – Baseline 2



More realistic but still tight...



Legend:

EM - engineering model

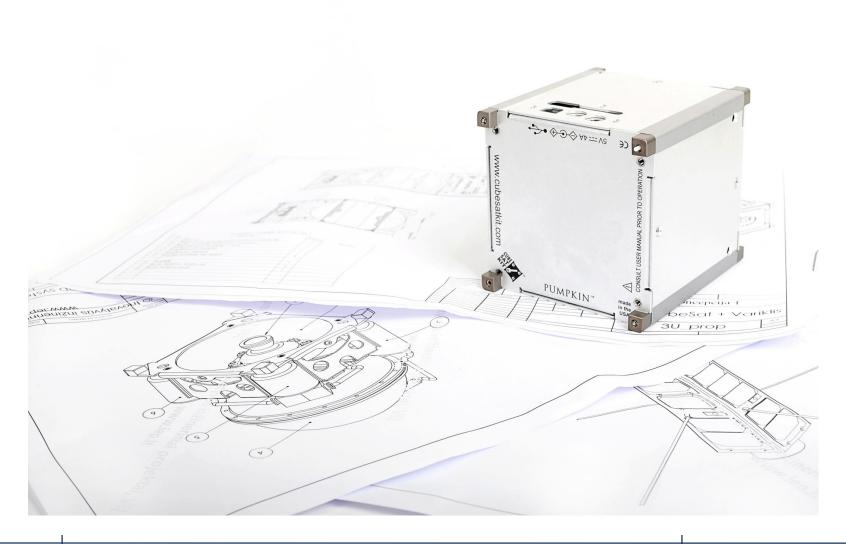
FM - Flight model

CDR - critical design review



System Design



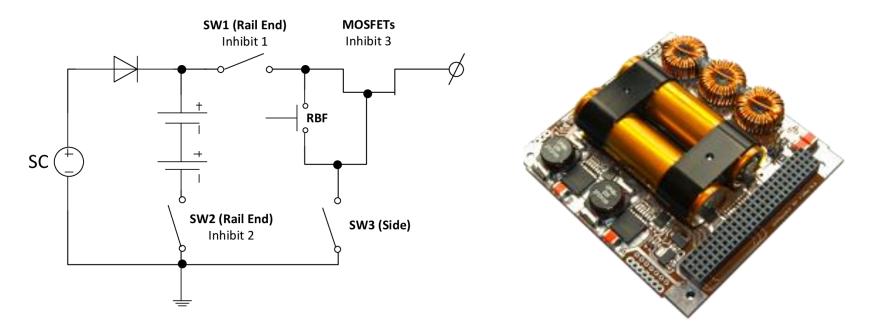




EPS



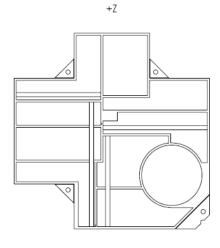
- GomSpace P31u as power management board
- expensive but reliable
- Design compatible with ISS safety requirements but individual testing was needed
- Kill switch circuit had to be modified IAW NASA requirements

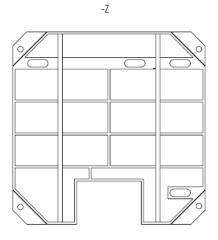


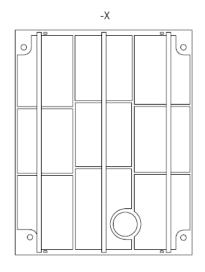


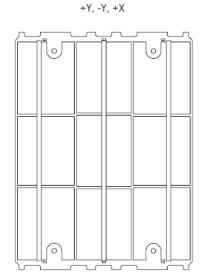
EPS – solar arrays









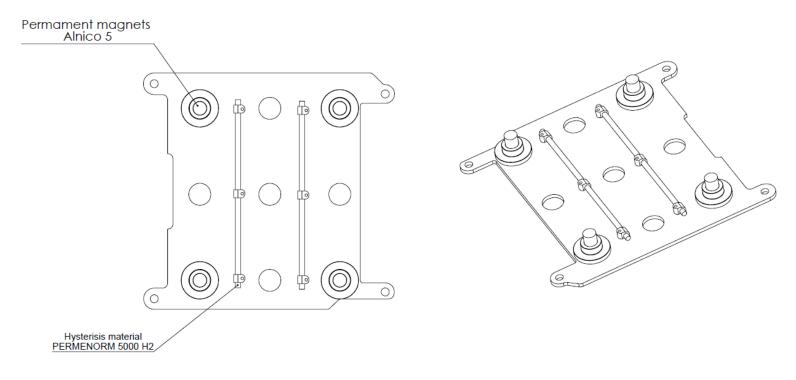


Lituanica\$AT-1 Si based Solar Array					
Panel	No of cells	I, A	U, V	P, W	
+7	9	0.15	4.5	0.75	
-Z	9	0.15	4.5	0.75	
-X	9	0.23	4.5	1	
+Y, -Y, +X	9	0.26	4.5	1.2	



ADCS





- Passive attitude control system:
 - Permanent magnet(-s): AlNiCo-5, dipole strength 0.6 A/m2 (z axis)
 - Hysteresis rods: PermeNorm 5000 H2, 0.075 cm3 (x and y axes)



OB&DH



ARM Cortex-M4F Primary flight computer:

- Performs power management
- Reads and logs attitude and inertial sensor data
- Receives and interprets telecommands from main communications transceiver
- Sends telemetry to main communications transceiver
- Arduino ATMega 2560 secondary computer:
 - Controls the On board camera
 - Stores pictures in SD card flash memory
 - Controls the radio beacon
 - Routes EPS housekeeping data to the radio beacon







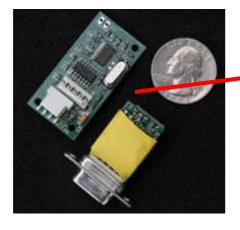


COMMUNICATIONS - hardware



- COTS FSK/GMSK transceiver Helium-100,
 - 9k6 baud
 - 2W RF output power
- FM beacon "Big Red Bee"
 - 100 mW output RF power
 - Flight heritage on ITupSAT-1 (>4 years in orbit)



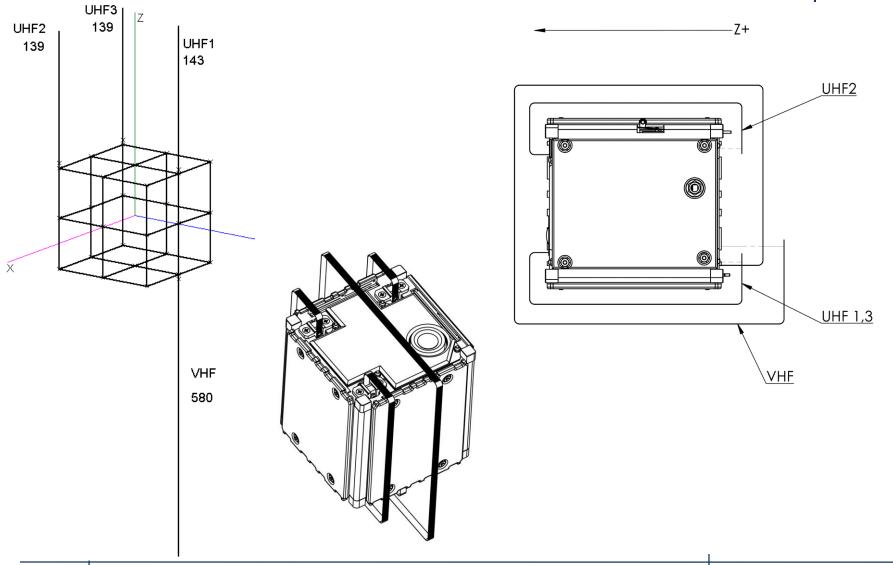






Antenna challenge

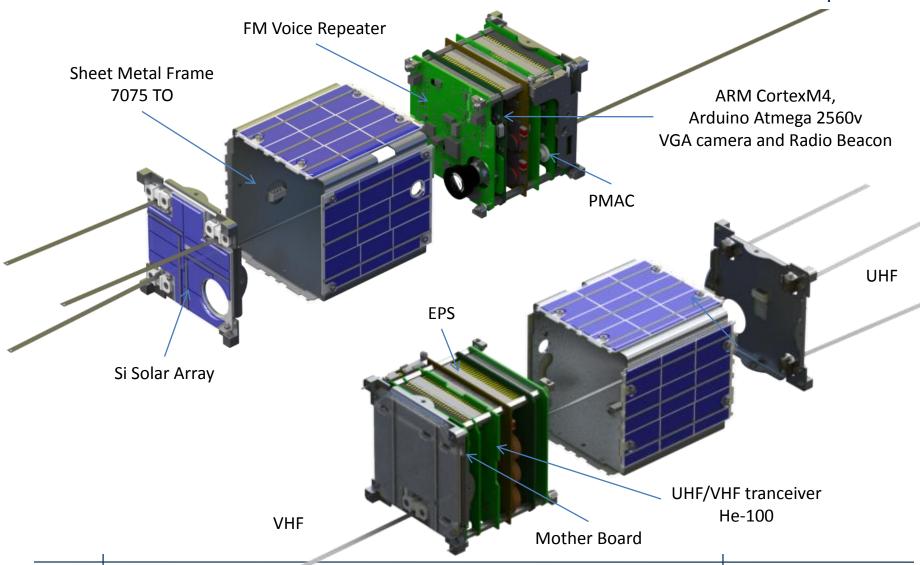






Structure







Payload - On Board Camera



Main requirements:

Low mass, low power consumption, image processing, convenient interface, compatibility with Arduino controllers.

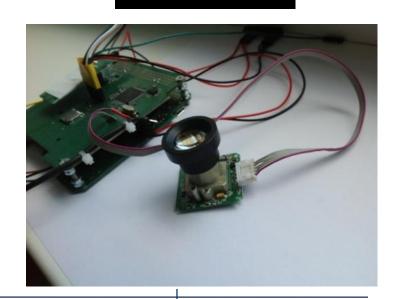
Selected option is LinkSprite JPEG Color Camera:

- > JPEG image compression
- > 3,3 5V power supply
- ➤ Size 32X32mm
- Current consumption: 80-100mA

Considered options:

- The GomSpace NanoCam C1U
- PX4FLOW Smart Camera*

Other options were mostly rejected due to unavailability of Convenient interface and image compression possibility





Payload – FM transponder



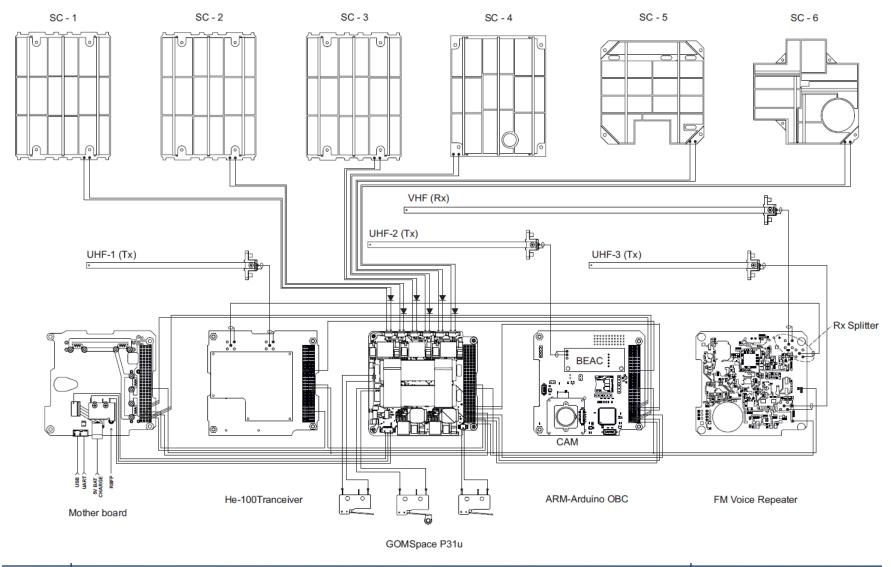
- The FM repeater is designed for placement in low Eearth orbit 1U Cubesat satellite.
- The main purpose is to widen the areal for amateur radio communications
- Operating temperature: -20° C to 70 ° C
- Weight (approx): 70 g
- Receiver system:
 - Dual conversion superheterodyne
 - 1st IF: 21.4 MHz, 2nd IF: 455 KHz
 - Frequency: 145.800-145.999 MHz
 - Receive sensitivity 0.18 uV (12 dB SINAD)
 - Selectivity: 12kHz
- Transmitter system:
 - Frequency: 435.000-438.000 MHz
 - RF Power Output: 150 mW
 - Modulation: F3E (FM)
 - Max deviation: ±6 kHz
 - Spurious emission: -60dB
- Activation: 67 Hz CTCSS tone





LituanicaSAT-1 Electric Diagram

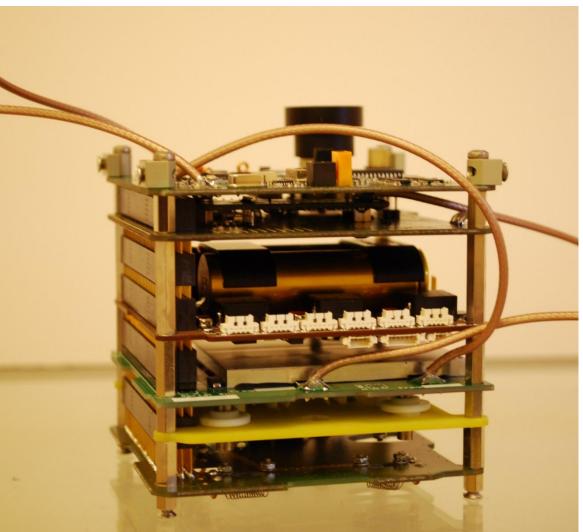


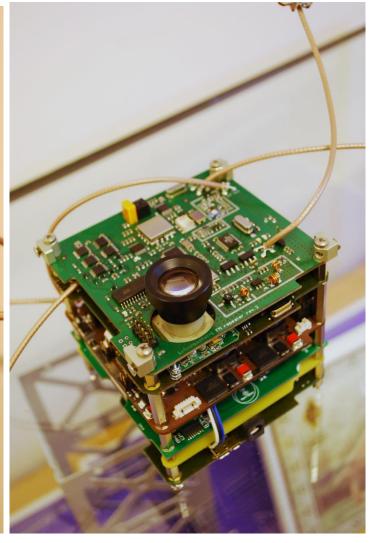




Protoflight model integration









Mission Operations







Launch and early operations







Deployment from ISS: 2014 02 28 7:30 UTC



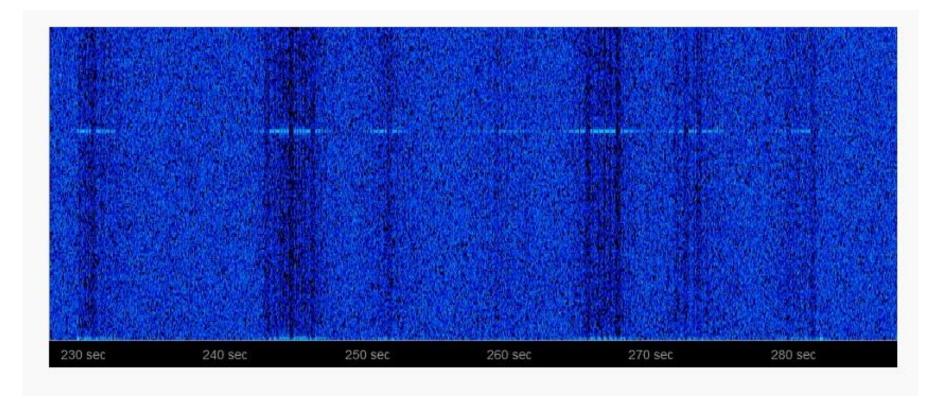




First orbit telemetry



FM beacon signal heard by DK3WN on 28/02/2014 08:45:00 UTC, 3 deg elevation pass: LY5N.....83 C021 0112 TN05 S63

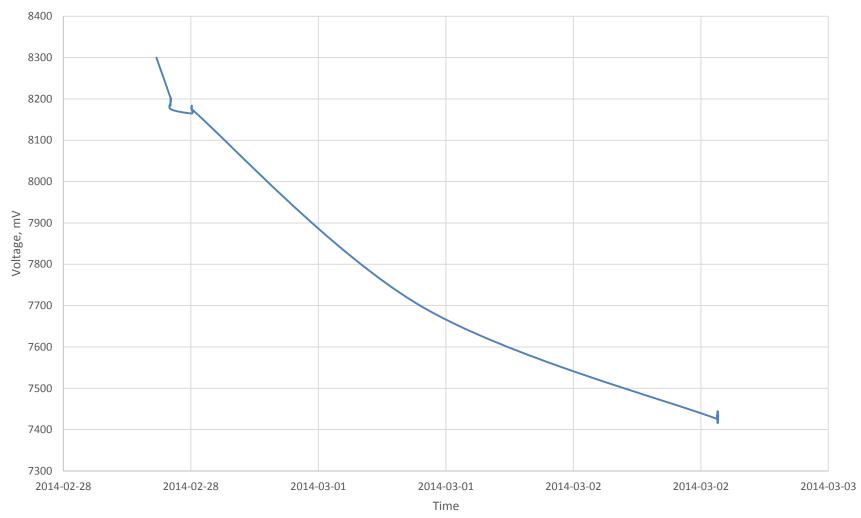




Early power problems







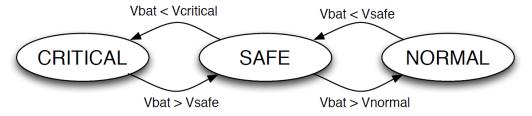


EPS fault analysis



- Abnormally low photo current from solar panels identified as the root cause of the failure
- Solar panel voltages appeared to be nominal
- > EPS under voltage protection prevented from critical failure but did not solve the

problem



Software level setpoints	Voltage level (V)	
Vnormal	7.4	
Vsafe	7.2	
Vcritical	6.5	

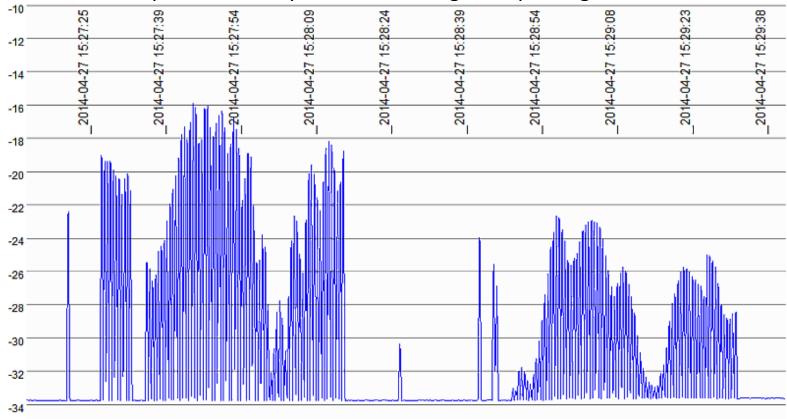
Solution: turn off the FM beacon (proved to be not so simple as it sounds)



COM troubleshooting



- ➤ Uplink budget proved to be less favorable than estimated during design (reliable uplinks were possible only using RF amplifier with 100W of output power)
- Downlink and uplink instability due to tumbling and spinning





First mission success







Successful transponder test



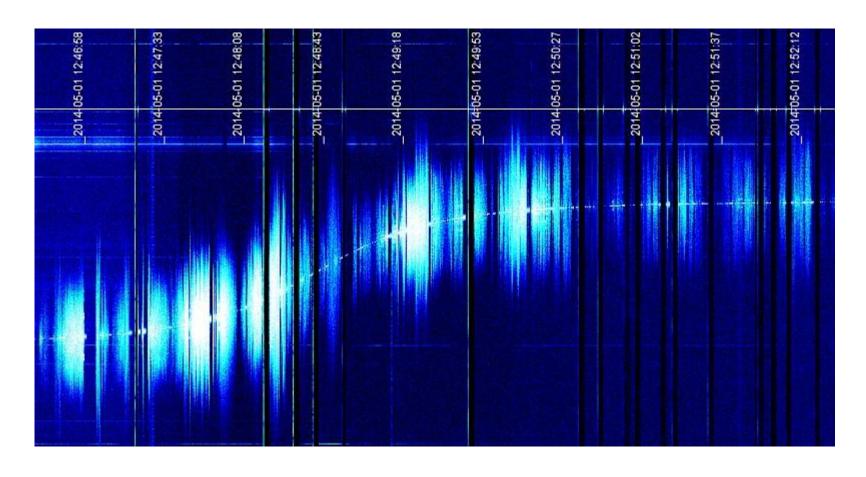


Image credit: Mike Rupprecht (url: http://www.dk3wn.info/p/?p=44725)



Feedback from radio amateurs







First picture from space

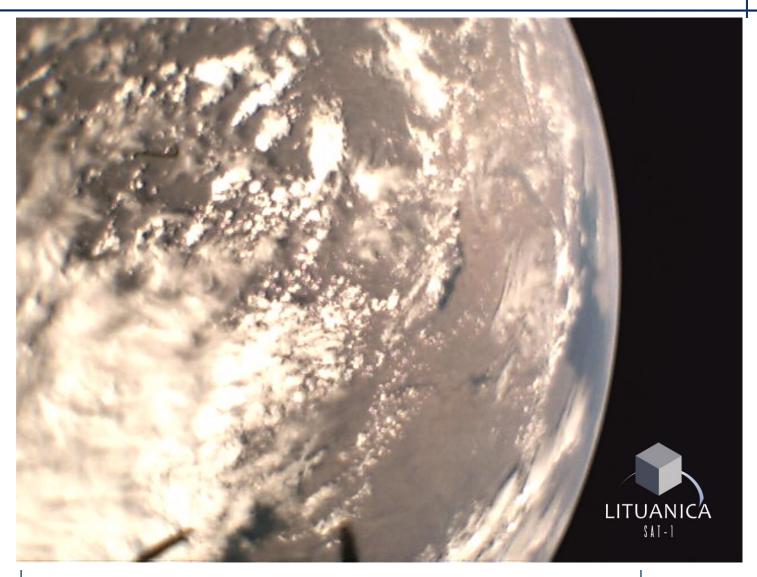






First glimpse at the Earth

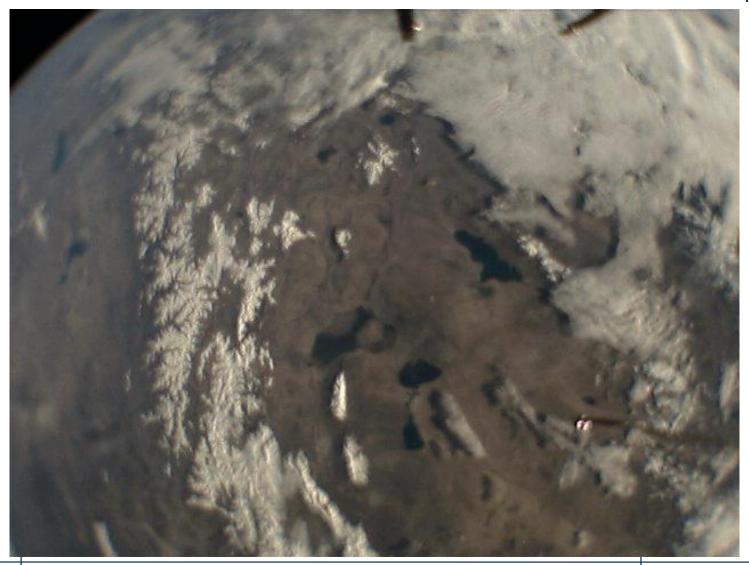






Spying over Mongolia







Lessons Learned



- Understand your stakeholder expectations
- Be prepared for budget overruns
- Avoid Protoflight philosophy
 - Risky (if something goes wrong you are in a big trouble)
 - Impossible to perform troubleshooting after launch
- Software integration and testing will take more time than you expect
- Most of the problems in orbit can be avoided by thorough testing on ground
- Keep your documentation up to date and <u>use it</u>



LituanicaSAT-2



Mission Objectives:

- To perform international science mission exploring lower thermosphere;
- To find new scientific and industrial partners for future collaboration;
- Technology demonstration of green propulsion system for CubeSat (deltaV = 150 m/s);
- To advance space science and technology in Lithuania;
- To develop commercial space grade nanosatellite components.

Project status:

- Flight Accepted;
- Detailed design completed and budget secured;
- Currently in phase C/D



LituanicaSAT-2 visualization (Above)
CubeSat propulsion system to be tested on LituanicaSAT-2 (Below)



Your questions



www.FB.com/LituanicaSAT-1 www.kosmonautai.lt

